

ΕΛΛΗΝΙΚΗ ΔΗΜΟΚΡΑΤΙΑ ΠΑΝΕΠΙΣΤΗΜΙΟ ΚΡΗΤΗΣ

Ψηφιακή Επεξεργασία Φωνής

Διάλεξη: Προσαρμόσιμα Ημιτονοειδή Μοντέλα

Παρουσίαση: Γιώργος Καφεντζής

Στυλιανού Ιωάννης Τμήμα Επιστήμης Υπολογιστών

Outline	Parametric Techniques	QHM	iQHM	adaptive QHM	extended aQHM	References

Adaptive Sinusoidal Models A tutorial

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- 3 iQHM
- 4 adaptive QHM
- 5 extended aQHM

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• Sinusoidal modeling of speech





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- Sinusoidal modeling of speech
- Dates back to the early 80ies



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- Essential assumption: local stationarity!

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- Essential assumption: local stationarity!
 - Speech is considered stationary in short time intervals

• (it is not, but it is a convenient assumption :-))



• Each frame is modeled as a sum of sinusoids:

$$s(t) = \sum_{k=-K}^{K} a_k e^{j(2\pi f_k t)}$$

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 - $\bullet\,$ Estimation of the sinusoidal parameters: FFT + peak picking

- Various improvements (e.g. quadratic interpolation)
- Highlight: no distinction between voiced and unvoiced frames



Signal reconstruction:

• Overlap Add method: $\hat{s}(t) = \sum_{k=-K}^{K} \hat{a}_k e^{j2\pi \hat{f}_k t}$



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 - Linear amplitude interpolation
 - Cubic phase interpolation



• Pros:



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- Pros:
 - Fast



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 - Fast
 - Good signal reconstruction



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 - Local stationarity assumption holds

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Sinusoidal model - Quatieri, McAulay, 1986

- Pros:
 - Fast
 - Good signal reconstruction
- Cons:
 - Local stationarity assumption holds
 - Not good modifications

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Sinusoidal model - Quatieri, McAulay, 1986

- Pros:
 - Fast
 - Good signal reconstruction
- Cons:
 - Local stationarity assumption holds
 - Not good modifications
 - Requires large windows



• Separate signal into periodic (deterministic) and aperiodic (stochastic) components:



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- Highlight: In voiced frames, $f_k = kf_0$: deterministic \longrightarrow harmonic

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 Harmonic + Noise model - Stylianou, 1993-1996

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- Pros:
 - Pitch synchronous analysis



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- Smaller window lengths



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 - \bullet Speech is not purely harmonic $(f_k\approx kf_0)$



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- Cons:
 - Local stationarity assumption holds
 - Depends on good f_0 estimation
 - Speech is not purely harmonic $(f_k\approx kf_0)$
 - ...this last observation is the motivation for the following model...

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$$s_d(t) = \sum_{k=-\kappa}^{\kappa} (a_k + tb_k) e^{j2\pi \hat{f}_k t} w(t)$$

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$$s_d(t) = \sum_{k=-K}^{K} (a_k + tb_k) e^{j2\pi \hat{f}_k t} w(t)$$

- a_k, b_k are complex numbers
- usually $f_k = kf_0$, where f_0 is considered as known

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- a_k, b_k are complex numbers
- usually $f_k = kf_0$, where f_0 is considered as known
- w(t) is the analysis window
- Again: Least Squares method for finding amplitudes

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• Window length pprox 3 pitch periods

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$$s_d(t) = \sum_{k=-K}^{K} (a_k + tb_k) e^{j2\pi \hat{f}_k t} w(t)$$

- a_k, b_k are complex numbers
- usually $f_k = kf_0$, where f_0 is considered as known
- w(t) is the analysis window
- Again: Least Squares method for finding amplitudes
- \bullet Window length \approx 3 pitch periods
- Reconstruction:

$$\hat{s}_d(t) = \sum_{k=-K}^{K} (\hat{a}_k + t\hat{b}_k) e^{j2\pi \hat{f}_k t}$$
(1)

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• HM versus QHM in frequency estimation - pure tone @ 100 Hz



- HM versus QHM in frequency estimation pure tone @ 100 Hz
- given frequency for both models: 90 Hz



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• Inst. amplitude:

$$M_k(t) = |a_k + tb_k| = \sqrt{(a_k^R + tb_k^R)^2 + (a_k^I + tb_k^I)^2}$$



• Inst. amplitude:

$$M_{k}(t) = |a_{k} + tb_{k}| = \sqrt{(a_{k}^{R} + tb_{k}^{R})^{2} + (a_{k}^{I} + tb_{k}^{I})^{2}}$$

• Inst. phase:
$$\Phi_k(t) = 2\pi \hat{f}_k t + tan^{-1} \frac{a_k + b_k}{a_k^R + tb_k^R}$$

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$$\Phi_k(t) = 2\pi \hat{f}_k t + tan^{-1} \frac{a_k^l + tb_k^l}{a_k^R + tb_k^R}$$

• Inst. frequency:
$$F_k(t) = \frac{1}{2\pi} \Phi'(t) = \hat{f}_k + \frac{1}{2\pi} \frac{a_k^R b_k' - a_k' b_k^R}{M_k^2(t)}$$

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• where x^{R}, x^{I} denote the real and imaginary part of x



HM vs QHM on frequency tracks - pure tone @ 100 Hz:



• Highlight: frequency correction mechanism



HM vs QHM on frequency tracks - pure tone @ 100 Hz:



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• Highlight: frequency correction mechanism

• Let's discuss a bit on that...



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Frequency domain view:

• Fourier Transform of the model:

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Frequency domain view:

- Fourier Transform of the model:
- Reminder:

$$x_k(t) = a_k e^{j2\pi f_k t} w(t) + t b_k e^{j2\pi f_k t} w(t)$$

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$$X_{k}(f) = a_{k}W(f - \hat{f}_{k}) + j\frac{b_{k}}{2\pi}W'(f - \hat{f}_{k})$$
(2)

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• where $W(f) = FT\{w(t)\}$ and W'(f) = dW(f)/df.

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$$W(f) = FT\{w(t)\}$$
 and $W'(f) = dW(f)/df$.

• Projecting b_k to a_k :

$$b_k = \rho_{1,k} a_k + \rho_{2,k} j a_k \tag{3}$$

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$$W(f) = FT\{w(t)\}$$
 and $W'(f) = dW(f)/df$

$$b_k = \rho_{1,k} a_k + \rho_{2,k} j a_k \tag{3}$$

• Then,

$$X_{k}(f) = a_{k} \left[W(f - \hat{f}_{k}) - \frac{\rho_{2,k}}{2\pi} W'(f - \hat{f}_{k}) + j \frac{\rho_{1,k}}{2\pi} W'(f - \hat{f}_{k}) \right]$$
(4)



• Taylor series expansion of
$$W(f - \hat{f}_k - \frac{\rho_{2,k}}{2\pi})$$
:

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• Taylor series expansion of $W(f - \hat{f}_k - \frac{\rho_{2,k}}{2\pi})$:

$$W(f - \hat{f}_k - \frac{\rho_{2,k}}{2\pi}) = W(f - \hat{f}_k) - \frac{\rho_{2,k}}{2\pi}W'(f - \hat{f}_k) + O(\rho_{2,k}^2W''(f - \hat{f}_k))$$
(5)

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 If the value of term W"(f) at f_k is small, then for small values of ρ_{2,k}, it is: Outline Parametric Techniques QHM iQHM adaptive QHM extended aQHM References

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• Taylor series expansion of $W(f - \hat{f}_k - \frac{\rho_{2,k}}{2\pi})$:

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• If the value of term W''(f) at f_k is small, then for small values of $\rho_{2,k}$, it is:

$$W(f - \hat{f}_k - \frac{\rho_{2,k}}{2\pi}) \approx W(f - \hat{f}_k) - \frac{\rho_{2,k}}{2\pi}W'(f - \hat{f}_k)$$
 (6)

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• Taylor series expansion of $W(f - \hat{f}_k - \frac{\rho_{2,k}}{2\pi})$:

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 (6)

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• So,

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$$X_k(f) \approx a_k \left[W(f - \hat{f}_k - \frac{\rho_{2,k}}{2\pi}) + j \frac{\rho_{1,k}}{2\pi} W'(f - \hat{f}_k) \right]$$
 (7)



• which goes back in time domain as...





• which goes back in time domain as...

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$$x_k(t) \approx a_k \left[e^{j(2\pi \hat{f}_k + \rho_{2,k})t} + \rho_{1,k} t e^{j2\pi \hat{f}_k t} \right] w(t)$$
 (8)



• which goes back in time domain as...

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$$x_k(t) \approx a_k \left[e^{j(2\pi \hat{f}_k + \rho_{2,k})t} + \rho_{1,k} t e^{j2\pi \hat{f}_k t} \right] w(t)$$
(8)

• Then, $\rho_{2,k}/2\pi$ can be an estimator of the frequency error η_k :

$$\hat{\eta}_k = \rho_{2,k}/2\pi = \frac{1}{2\pi} \frac{a_k^R b_k' - a_k' b_k^R}{|a_k|^2} \tag{9}$$

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• which goes back in time domain as...

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$$x_k(t) \approx a_k \left[e^{j(2\pi \hat{f}_k + \rho_{2,k})t} + \rho_{1,k} t e^{j2\pi \hat{f}_k t} \right] w(t)$$
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• Then, $\rho_{2,k}/2\pi$ can be an estimator of the frequency error η_k :

$$\hat{\eta}_{k} = \rho_{2,k}/2\pi = \frac{1}{2\pi} \frac{a_{k}^{R} b_{k}' - a_{k}' b_{k}^{R}}{|a_{k}|^{2}}$$
(9)

• In other words, QHM suggests a frequency correction to the input frequencies \hat{f}_k (or a frequency estimator). This suggestion is however conditional on the magnitude of $\rho_{2,k}$ and the value of term W''(f) at f_k

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• which goes back in time domain as...

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$$x_k(t) \approx a_k \left[e^{j(2\pi \hat{f}_k + \rho_{2,k})t} + \rho_{1,k} t e^{j2\pi \hat{f}_k t} \right] w(t)$$
(8)

• Then, $\rho_{2,k}/2\pi$ can be an estimator of the frequency error η_k :

$$\hat{\eta}_{k} = \rho_{2,k}/2\pi = \frac{1}{2\pi} \frac{a_{k}^{R} b_{k}' - a_{k}' b_{k}^{R}}{|a_{k}|^{2}}$$
(9)

- In other words, QHM suggests a frequency correction to the input frequencies \hat{f}_k (or a frequency estimator). This suggestion is however conditional on the magnitude of $\rho_{2,k}$ and the value of term W''(f) at f_k
- Also, the correction term depends on the window mainlobe width

Outline	Parametric Techniques	QHM	iQHM	adaptive QHM	extended aQHM	References
Outline						

- Parametric Techniques
- 2 QHM



- 4 adaptive QHM
- 5 extended aQHM

6 References



• This frequency updating mechanism provides frequencies which can be used in the model iteratively and result in better parameter estimation (a_k, b_k)



• This frequency updating mechanism provides frequencies which can be used in the model iteratively and result in better parameter estimation (a_k, b_k)

• This iterative parameter estimation is referred to as the *iterative QHM*



HM versus iQHM in frequency estimation - speech signal:



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Noise robustness:



Figure: Noise Robustness

Outline	Parametric Techniques	QHM	iQHM	adaptive QHM	extended aQHM	References
iterative QHM						

• Pros:



• Pros:

• Linear amplitude evolution





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- Pros:
 - Linear amplitude evolution
 - Frequency mismatch correction: $\eta_k = f_k \hat{f}_k$



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 - Linear amplitude evolution
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- Cons:



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- Pros:
 - Linear amplitude evolution
 - Frequency mismatch correction: $\eta_k = f_k \hat{f}_k$
- Cons:
 - Needs larger analysis window



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- Pros:
 - Linear amplitude evolution
 - Frequency mismatch correction: $\eta_k = f_k \hat{f}_k$
- Cons:
 - Needs larger analysis window
 - And what about...

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 - Linear amplitude evolution
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 - And what about...
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- Cons:
 - Needs larger analysis window
 - And what about...
 - local stationarity??
 - Speech is non stationary even in very short time intervals

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- Pros:
 - Linear amplitude evolution
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• iQHM still holds the local stationary assumption

Outline	Parametric Techniques	QHM	iQHM	adaptive QHM	extended aQHM	References
Outli	ne					

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 Adaptive Quasi-Harmonic Model
 Image: Compared to the second se

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• Adaptive models tackle the problem of local non stationarity[5] - How?

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 Adaptive Quasi-Harmonic Model

- Adaptive models tackle the problem of local non stationarity[5] How?
 - By projecting the signal onto non-stationary basis functions $e^{j\phi_k(t)}!$

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• Model:
$$s_d(t) = \sum_{k=-K}^{K} (a_k + tb_k) \Big(e^{j\phi_k(t)} \Big) w(t)$$

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• Definition of phase:

$$\breve{\phi}_k(t) = \hat{\phi}_k(t_{l-1}) + \int_{t_{l-1}}^t 2\pi \hat{f}_k(u) du$$

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• Adaptation algorithm can be found in [5]

QHM vs aQHM:



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Adaptation algorithm for aQHM

• Let $\hat{A}_k(t_l), \hat{f}_k(t_l), \hat{\phi}_k(t_l)$ denote the inst. amplitude, frequency, and phase at time instant t_l of the k^{th} component, with $l = 1, \dots, L$, where L is the number of frames:

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• Initialization: (QHM) 1) $\hat{f}_{k}^{0}(t_{l}) = \hat{f}_{k}^{0}(t_{l-1}) + \rho_{2,k}^{0}/2\pi$ 2) $\hat{A}_{k}^{0}(t_{l}) = |a_{k}^{0}|, \quad \hat{\phi}_{k}^{0}(t_{l}) = \angle a_{k}^{0}$ 3) $\hat{f}_{k}^{0}(t_{l+1}) = \hat{f}_{k}^{0}(t_{l})$

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Adaptation algorithm for <u>aQHM</u>

• Let $\hat{A}_k(t_l), \hat{f}_k(t_l), \hat{\phi}_k(t_l)$ denote the inst. amplitude, frequency, and phase at time instant t_l of the k^{th} component, with $l = 1, \dots, L$, where L is the number of frames:

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END

Outline
Parametric Techniques
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iQHM
adaptive QHM
extended aQHM
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Adaptation algorithm for aQHM
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 Initialization: (QHM) 1) $\hat{f}_{k}^{0}(t_{l}) = \hat{f}_{k}^{0}(t_{l-1}) + \rho_{2k}^{0}/2\pi$ 2) $\hat{A}_{l}^{0}(t_{l}) = |a_{l}^{0}|, \ \hat{\phi}_{l}^{0}(t_{l}) = \angle a_{l}^{0}$ 3) $\hat{f}_{\mu}^{0}(t_{l+1}) = \hat{f}_{\mu}^{0}(t_{l})$ • FOR adaptation $i = 1, 2, \cdots$ FOR frame $l = 1, 2, \dots, L$ Compute a'_k, b'_k using $\hat{\phi}_k^{l-1}(t)$ and (10) 2 Update $\hat{f}_{k}^{i}(t_{l})$ using (9) **3** Compute $\hat{A}_{k}^{i}(t_{l})$ and $\hat{\phi}_{k}^{i}(t_{l})$ FND Interpolation of the parameters $\{\hat{A}_{\iota}^{i}(t), \hat{f}_{\iota}^{i}(t), \hat{\phi}_{\iota}^{i}(t)\}$ END

Adaptive Quasi-Harmonic model

Synthetic signal:



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Adaptive Quasi-Harmonic model

Real Signal:



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Outline	Parametric Techniques	QHM	iQHM	adaptive QHM	extended aQHM	References
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• Pros:

• Phase adaptation, non-parametric approach



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• Pros:

- Phase adaptation, non-parametric approach
- Local nonstationarity is partially solved



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- High signal-to-reconstruction error ratio (SRER): $SRER = 20 \log_{10} \frac{\sigma_{\hat{x}(t)}}{\sigma_{\hat{x}(t)-x(t)}}$



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• Cons:



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• Needs larger analysis window (as iQHM)



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Cons:

- Needs larger analysis window (as iQHM)
- Amplitudes are not adapted to the signal

Outline	Parametric Techniques	QHM	iQHM	adaptive QHM	extended aQHM	References
Outli	ne					

- Parametric Techniques
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- 3 iQHM
- 4 adaptive QHM
- 5 extended aQHM

6 References

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Pantazis, Stylianou, Rosec, 2011

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Synthetic signal:



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Synthetic signal:

• Robustness in noise is demonstrated:

Extended Adaptive Quasi-Harmonic model

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	MAE scores and SRER						
•	SNR	Model	$a_1(t)$	$a_2(t)$	$F_1(t)$	$F_2(t)$	SRER(dB)
	∞	aQHM	0.2380	0.1842	7.6105	9.1731	22.6
		eaQHM	0.0889	0.0949	5.9217	7.0505	42.0
	10 dB-	aQHM	0.2317	0.1860	8.6071	9.0302	10.7
		eaQHM	0.1490	0.1476	8.0513	8.1022	10.9

Table: MAE scores and SRER for aQHM and eaQHM for 10^4 Monte Carlo simulations.

Extended Adaptive Quasi-Harmonic model

Real Signal:



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Adaptation algorithm for eaQHM

Let Â_k(t_l), f_k(t_l), φ̂_k(t_l) denote the inst. amplitude, frequency, and phase at time instant t_l of the kth component, with l = 1, · · · , L, where L is the number of frames:

 Initialization: (QHM) 1) $\hat{f}_{k}^{0}(t_{l}) = \hat{f}_{k}^{0}(t_{l-1}) + \rho_{2k}^{0}/2\pi$ 2) $\hat{A}_{l}^{0}(t_{l}) = |a_{l}^{0}|, \ \hat{\phi}_{l}^{0}(t_{l}) = \angle a_{l}^{0}$ 3) $\hat{f}_{\mu}^{0}(t_{l+1}) = \hat{f}_{\mu}^{0}(t_{l})$ • FOR adaptation $i = 1, 2, \cdots$ FOR frame $l = 1, 2, \dots, L$ Compute a'_k, b'_k using $\hat{\phi}_k^{l-1}(t)$ and (11) 2 Update $\hat{f}_{\iota}^{i}(t_{l})$ using (9) 3 Compute $\hat{A}_{k}^{i}(t_{l})$ and $\hat{\phi}_{k}^{i}(t_{l})$ FND Interpolation of the parameters $\{\hat{A}_{k}^{i}(t), \hat{f}_{k}^{i}(t), \hat{\phi}_{k}^{i}(t)\}$ END

Analysis-Synthesis System

• Seperate speech into two parts: deterministic and stochastic

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Analysis-Synthesis System

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 Deterministic part: a sum of non-stationary sinusoids (ea/aQHM)

Analysis-Synthesis System

- Seperate speech into two parts: deterministic and stochastic
- Deterministic part: a sum of non-stationary sinusoids (ea/aQHM)
- Stochastic part: time and frequency modulated (energy-based envelope and AR modeling)

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• Very high quality of speech signal reconstruction

Outline	Parametric Techniques	QHM	iQHM	adaptive QHM	extended aQHM	References
Outline						

- Parametric Techniques
- 2 QHM
- 3 iQHM
- 4 adaptive QHM
- 5 extended aQHM




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Outline
Parametric Techniques
QHM
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adaptive QHM
extended aQHM
References

Time for Questions!
Image: Comparison of the second sec

Thank you for your attention! Any questions? :-)

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