Adaptive Sinusoidal Modeling

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- **1** Sinusoidal Modeling
- **2** Advanced Modeling
- 3 QHM
 - Validation
- 4 AQHM
 - Description
 - Validation
 - AM-FM decomposition
- 5 EAQHM
- 6 APPLICATIONS
 - Speech technologies
- **7** Key papers
- 8 References

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• Sinusoidal Model:

$$x(t) = \sum_{k=-K}^{K} \gamma_k e^{j2\pi f_k t}$$

• Special case, Harmonic Model:

$$x(t) = \sum_{k=-K}^{K} \gamma_k e^{j2\pi k f_0 t}$$

• Estimation of parameters (Linear approach):

$$\gamma = \mathcal{F}_{f_k} \mathbf{s}$$

• Model Evaluation, Mean-Squared Error (MSE):

$$\epsilon = \int_{w} |s(t) - x(t)|^2 dt$$

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Outline Sinusoidal Modeling Advanced Modeling QHM aQHM eaQHM Applications Key papers References

IQHM, AQHM, EAQHM, AHM

Towards Adaptive Sinusoidal Models

• Sinusoidal representation for a speech/signal frame:

$$x(t) = \left(\sum_{k=-K}^{K} a_k e^{j2\pi f_k t}\right) w(t)$$

- Methods:
 - FFT-based methods (i.e., QIFFT [Abe et al., 2004-05, [2] [3]])
 - Subspace methods
 - Least Squares (LS) method
- Frequency mismatch:

$$\hat{f}_k = f_k + \eta_k$$

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• QHM (de Prony 1795, Laroche [4] (1989), Stylianou 1993, Pantazis [5] (2008, 2011)):

$$x(t) = \left(\sum_{k=-K}^{K} (a_k + tb_k)e^{j2\pi \hat{f}_k t}\right) w(t)$$

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• QHM in the frequency domain:

$$X_k(f) = a_k W(f - \hat{f}_k) + j \frac{b_k}{2\pi} W'(f - \hat{f}_k)$$

• **Decomposition of** b_k : $b_k = \rho_{1,k}a_k + \rho_{2,k}ja_k$

• Then

$$X_{k}(f) = a_{k} \left[W(f - \hat{f}_{k}) - \frac{\rho_{2,k}}{2\pi} W'(f - \hat{f}_{k}) + j \frac{\rho_{1,k}}{2\pi} W'(f - \hat{f}_{k}) \right]$$

• and taking into account:

$$W(f - \hat{f}_k - \frac{\rho_{2,k}}{2\pi}) = W(f - \hat{f}_k) - \frac{\rho_{2,k}}{2\pi}W'(f - \hat{f}_k) + O(\rho_{2,k}^2W''(f - \hat{f}_k))$$

• Approximation of the kth component of QHM

$$X_k(f) \approx \mathsf{a}_k \left[W(f - \hat{f}_k - \frac{\rho_{2,k}}{2\pi}) + j \frac{\rho_{1,k}}{2\pi} W'(f - \hat{f}_k) \right]$$

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• Back to the time-domain:

$$x_k(t) pprox a_k \left[e^{j(2\pi \hat{f}_k + \rho_{2,k})t} + \rho_{1,k} t e^{j2\pi \hat{f}_k t}
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• Initially, we assumed:

$$x_k(t) = a_k \left[e^{j(2\pi(\hat{f}_k + \eta_k))t} \right] w(t)$$

• in other words, it is suggested:

$$\hat{\eta}_k = \rho_{2,k}/2\pi$$

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Constraints

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- We would like small value for W''(f) at f_k
- W''(f) is influenced by the length, T, of the analysis window, i.e., for rectangular window: $W''(f) \propto T^3$
- So ... we would like a short analysis window
- But ... long analysis window provides robustness
- Length of the window \rightleftharpoons bandwidth

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Assume

$$y(t) = \alpha e^{j(2\pi \hat{f} t + \eta t)}$$

modeled by QHM as

$$x(t)=(a+tb)e^{j(2\pi \widehat{f}t)}$$
 $-T\leq t\leq T$

• LS solution provides:

$$a = \alpha \frac{\sin(\eta T)}{\eta T}$$

$$b = \alpha \ 3j(\frac{\sin(\eta T)}{\eta^2 T^3} - \frac{\cos(\eta T)}{\eta T^2})$$

• Frequency mismatch estimate:

$$\hat{\eta} = 3\left(\frac{1}{\eta T^2} - \frac{\cot(\eta T)}{T}\right)$$

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Combining Influences



• Iteratively, the bias can be removed when $|\eta| < B/3$, where B is the bandwidth of the squared analysis window, $\beta \in \mathbb{R}$

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Adaptive Sinusoidal Modeling

ROBUSTNESS AGAINST ADDITIVE NOISE

• Signal contaminated by noise:

$$y(t) = \sum_{k=1}^{4} a_k e^{j2\pi f_k} + v(t)$$

• Mean Squared Error (MSE):

$$MSE\{\hat{f}_{k}\} = \frac{1}{M} \sum_{i=1}^{M} |\hat{f}_{k}(i) - f_{k}|^{2}$$
$$MSE\{\hat{a}_{k}\} = \frac{1}{M} \sum_{i=1}^{M} |\hat{a}_{k}(i) - a_{k}|^{2}$$

- Comparison with Cramer-Rao Bounds (CRB) and QIFFT (Abe et al. 2004)
- 10000 Monte Carlo simulations

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MSE OF FREQUENCIES AS A FUNCTION OF SNR.



MSE OF AMPLITUDES AS A FUNCTION OF SNR.



- The approximation made in QHM is valid provided that the frequency mismatch lies in a specific interval.
- This interval is a function of the bandwidth of the analysis window.
- Robustness of QHM against noise was tested and verified.
- It can be shown that iterative QHM is equivalent to (an approximate) Gauss-Newton method.
- There are also relations between QHM and Reassigned Spectrum

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Notes on QHM

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QHM AND GAUSS-NEWTON METHOD

• Assuming we have N samples of $x(t) = ce^{j\omega t}w(t)$

Approximate Gauss-Newton solution for frequency

$$\omega^{(1)} = \omega^{(0)} - \mathcal{R} \left\{ \frac{\sum_{t=-N}^{N} t w^{2}(t) x(t) e^{-j\omega^{(0)}t}}{c^{(0)} \sum_{t=-N}^{N} t^{2} w^{2}(t)} \right\}$$

• QHM

$$x(t) = (c+tb)e^{j\omega t}w(t)$$

with

$$\omega^{(1)} = \omega^{(0)} + \rho_2
 = \omega^{(0)} - \mathcal{R}\left\{\frac{jb^{(0)}}{c^{(0)}}\right\}$$

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$$b^{(0)} = \frac{\sum_{t=-N}^{N} t w^2(t) x(t) e^{-j \omega^{(0)} t}}{\sum_{t=-N}^{N} t^2 w^2(t)}$$

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with $\omega^{(1)} = \omega^{(0)} + \rho_2$ $= \omega^{(0)} - \mathcal{R} \left\{ \frac{jb^{(0)}}{c^{(0)}} \right\} \Leftarrow$ where $= \frac{\sum_{t=-N}^{N} t w^{2}(t) x(t) e^{-j \omega^{(0)} t}}{\sum_{t=-N}^{N} t^{2} w^{2}(t)}$ $b^{(0)}$ yannis@csd.uoc.gr Adaptive Sinusoidal Modeling

EVALUATION: RMSE FOR FREQUENCY

ightarrow SNR = 0dB, N = 100 (left), N = 500 (right). CRB: Cramer-Rao lower bound for frequency estimation



EVALUATION: RMSE FOR AMPLITUDE

ightarrow SNR = 0dB, N = 100 (left), N = 500 (right). CRB: Cramer-Rao lower bound for amplitude estimation



REASSIGNED SPECTRUM

• Time relocation:

$$\hat{\tau} = -\frac{\partial \phi(\tau, \omega)}{\partial \omega} = \tau - \Re\left(\frac{X_{Tw}(\tau, \omega)}{X(\tau, \omega)}\right)$$

where

$$X_{Tw}(\tau,\omega) = -\sum_{t=-N}^{N} tw(t)x(t+\tau)e^{-j\omega(t+\tau)}$$

• Frequency relocation:

$$\hat{\omega} = \omega + \frac{\partial \phi(\tau, \omega)}{\partial \tau} = \omega + \Im \left(\frac{X_{\mathcal{D}w}(\tau, \omega)}{X(\tau, \omega)} \right)$$

where

$$X_{\mathcal{D}w}(\tau,\omega) = -\sum_{t=-N}^{N} \underbrace{\frac{dw(t)}{dt}}_{t} x(t+\tau) e^{-j\omega(t+\tau)}$$

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REASSIGNED SPECTRUM AND QHM

- QHM: $x(t) = (a + tb)e^{j\omega t}w(t)$ with $b = \rho_1 a + \rho_2 j a_1$
- Then, it can be shown:

$$\hat{\tau} = \tau + \frac{W_2}{W_0}\rho_1$$

and (in case of using Gaussian windows):

$$\hat{\omega} = \omega + \frac{W_2}{W_0}\rho_2$$

where

$$W_k = \sum_{t=-N}^N t^k w(t)$$

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FREQUENCY MISMATCH ESTIMATION ERROR



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FROM QHM TO ADAPTIVE QHM, AQHM [7]

• QHM (stationarity assumption):

$$x(t) = \left(\sum_{k=-\kappa}^{\kappa} (a_k + tb_k)e^{2\pi j f_k t}\right) w(t)$$

• Adaptive QHM (aQHM):

$$x(t) = \left(\sum_{k=-K}^{K} (a_k + tb_k)e^{j\tilde{\phi}_k(t)}\right)w(t)$$

where

$$ilde{\phi}_k(t)=2\pi\int_0^t f_k(s)ds+arphi, \ t\in[0,T]$$

is the estimated instantaneous phase.

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FROM QHM TO AQHM; GRAPHICALLY



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FRAME RATE IN AQHM

- One sample: no interpolation between estimations
- Higher rates (i.e., 5ms, 10ms): Interpolation between estimates is required:
 - Amplitudes are linearly interpolated
 - Frequencies are interpolated with splines
 - Phases are interpolated by integration of instantaneous frequency

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EXAMPLE OF ESTIMATION IN AQHM: NO ITERATION (QHM)



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Adaptive Sinusoidal Modeling

EXAMPLE OF ESTIMATION IN AQHM: ONE ITERATION



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EXAMPLE OF ESTIMATION IN AQHM: TWO ITERATIONS



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Adaptive Sinusoidal Modeling

• Let us consider as example:

```
x(t) = (11 - 340t + 4000t^2)e^{j2\pi(280t + 19500t^2)}
```

- and frequency mismatch: $|f_k \zeta_k| = 35Hz$, using Hamming window
- Consider simplified approaches: Sinusoidal-based analysis (SM)
- Mean Absolute Error (MAE) [frame rate: one sample]

	AM	FM (Hz)
<i>QHM</i> , 10ms	0.46	2.15
aQHM(1)		
<i>SM</i> , 10ms	0.44	3.08

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- Mean Absolute Error (MAE) [frame rate: one sample]

	AM	FM (Hz)
<i>QHM</i> , 10ms	0.46	2.15
aQHM (1)	0.008	0.006
<i>SM</i> , 10ms	0.44	3.08

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QHM REMINDER

• QHM:

$$x(t) = \left(\sum_{k=-K}^{K} (a_k + tb_k)e^{2\pi j f_k t}\right) w(t)$$

• Instantaneous parameters:

$$\begin{aligned} A_k(t) &= \sqrt{(a_k^R + tb_k^R)^2 + (a_k^I + tb_k^I)^2} \\ \Phi_k(t) &= 2\pi f_k t + atan \frac{a_k^I + tb_k^I}{a_k^R + tb_k^R} \\ F_k(t) &= f_k + \frac{1}{2\pi} \frac{a_k^R b_k^I - a_k^I b_k^R}{M_k^2(t)} = f_k + \frac{1}{2\pi} \rho_{2,k} \end{aligned}$$

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QHM AND AM-FM DECOMPOSITION

• AM-FM signal

$$y(t) = \sum_{k=1}^{K(t)} \underline{a_k(t)} \cos(\phi_k(t)),$$

• Taylor series expansion of the instantaneous phase of *k*th component:

$$\phi_k(t) = 2\pi\zeta_k t + \sum_{i=0}^{\infty} \phi_{k,i} \frac{t^i}{i!}$$

• Instantaneous frequency of the kth component at t = 0:

$$\nu_k(0) = \zeta_k + \frac{\phi_{k,1}}{2\pi}$$

• ... and previously we had:

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RECONSTRUCTION ERRORS WITH QHM, AQHM, SM



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AQHM: AM-FM DECOMPOSITION OF VOICED SPEECH

Signal Reconstruction

$$\hat{x}(t) = \sum_{k=1}^{K} \hat{A}_k(t) \cos\left(\hat{\Phi}_k(t)\right)$$

- Test on 5 minutes of 20 female and male voiced speech (TIMIT)
- Average Signal-to-Error Reconstruction Ratio (in dB)

	Male	Female
QHM	23.9	29.1
<i>aQHM</i> (3)	29.1	34.1
SM	17.2	21.1

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EXTENDED AQHM

• Recall aQHM:

$$x(t) = \sum_{k=-K}^{K} (a_k + tb_k) e^{j \tilde{\phi}_k(t)}$$

• Extended aQHM:

$$x(t) = \sum_{k=-K}^{K} (a_k + tb_k) \alpha(t) e^{j \tilde{\phi}_k(t)}$$

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Outline Sinusoidal Modeling Advanced Modeling QHM aQHM eaQHM Applications Key papers References

AM-FM MODELING: AQHM



Outline Sinusoidal Modeling Advanced Modeling QHM aQHM eaQHM Applications Key papers References

AM-FM MODELING: EXTENDED AQHM



Comparing Adaptive Models



STOP MODELING



STOP MODELING



LARGE SCALE EVALUATION

Global Signal to Reconstruction Error Ratio (dB)						
Model	/p/	/t/	/k/	/b/	/d/	/g/
SM	12.7	12.8	12.4	16.6	14.9	15.3
aQHM	19.9	20.6	21.7	28.3	26.9	27.5
eaQHM	25.4	25.7	27.2	32.9	32.2	32.9

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• High quality pitch scale modification

- Within glottal cycle formant tracking and modifications towards voice conversion
- Free pre-echo effect in time scaling
- Emotion detection and control

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Speech Synthesis

- UNIT SELECTION BASED: fast synthesis, smooth trajectories, high quality prosodic modifications, voice conversion
- STATISTICAL MODELING: *naturally* smooth trajectories, articulators tracking, adaptation and controllability, modulations
- Sinusoidal models work nicely with DNNs

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• Robust to noise filter bank estimation

- Data driven dynamic information
- High-resolution modulations
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• Jitter and shimmer estimators

- Vocal fatigue
- Robust estimation in spasmodic dysphonia
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Key papers to read

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THANK YOU for your attention on this part as well!

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